Optimizing Ranking Models in an Online Setting



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Online Learning to Rank

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Online Learning to Rank: **learn by interacting with users**.

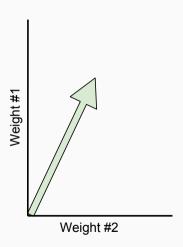
Solves most of the problems of expert-annotations:

- Interactions are virtually free if you have users.
- User behaviour gives implicit feedback.

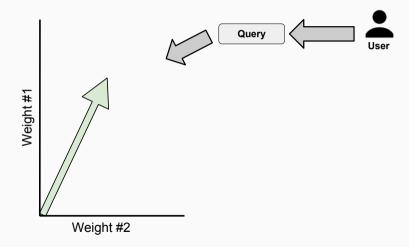
These methods have to handle:

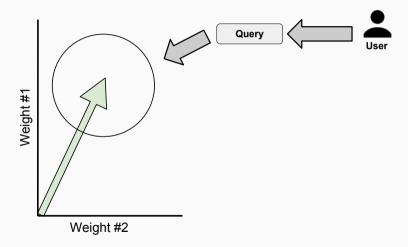
- Noise: Users click for unexpected reasons.
- Biases: Interactions are affected by position and selection bias.

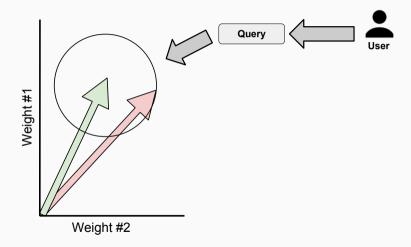
Dueling Bandit Gradient Descent

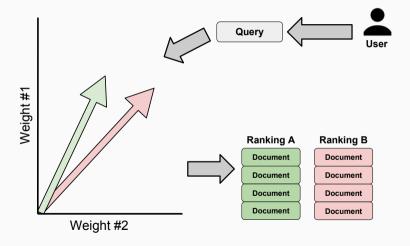


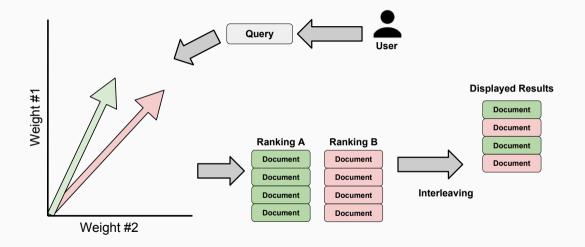


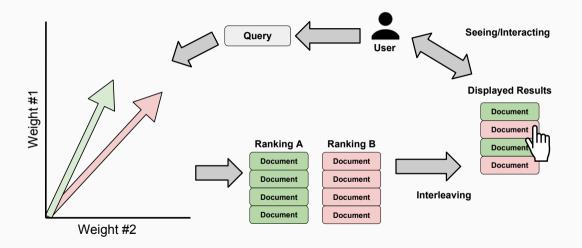


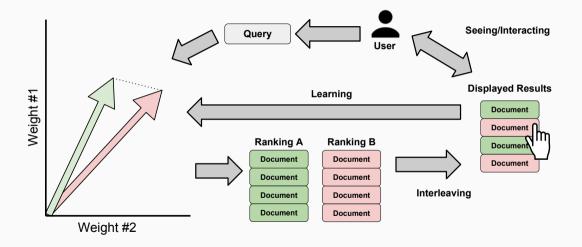


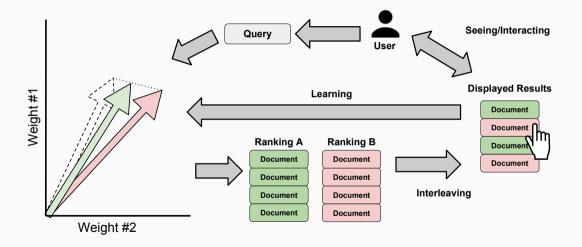












Dueling Bandit Gradient Descent

Basis of the online LTR field, virtually everything is an extension of DBGD: (Yue and Joachims, 2009; Schuth et al., 2016; Hofmann et al., 2013; Zhao and King, 2016; Wang et al., 2018).

Pairwise Differentiable Gradient

Descent

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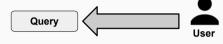


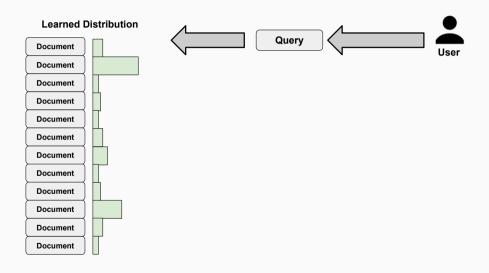
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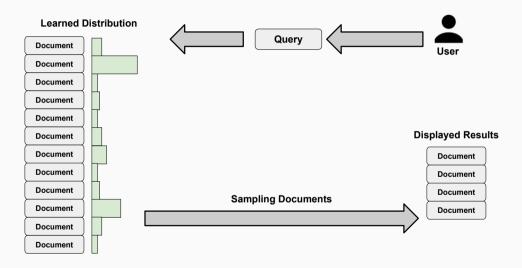
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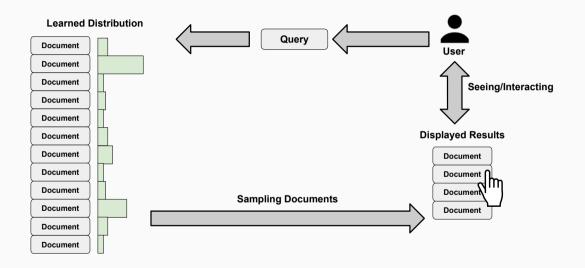
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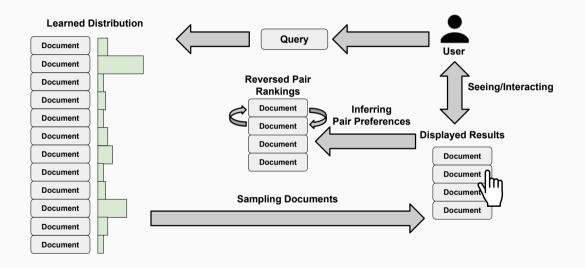
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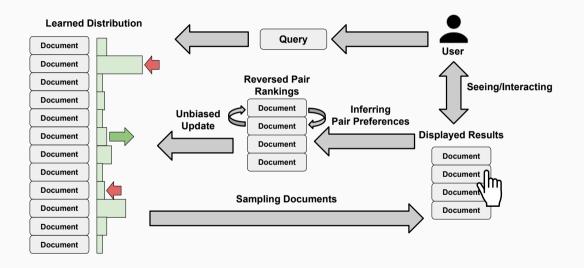












Limitations of Existing Results

Limitations of Previous Existing Results

Comparison based on previous work (Oosterhuis and de Rijke, 2018):

- Pairwise Differentiable Gradient Descent outperforms DBGD.
- Dueling Bandit Gradient Descent has proven sublinear regret bounds.

Problems with the current state of affairs:

- Past comparisons are based on low-noise, cascading click models,
 Pairwise Differentiable Gradient Descent assumes cascading behaviour!
- There is a conflict between the proven regret bounds of Dueling Bandit Gradient Descent and its observed performance.

Our contribution

First, we critically look at the regret bounds of Dueling Bandit Gradient Descent:

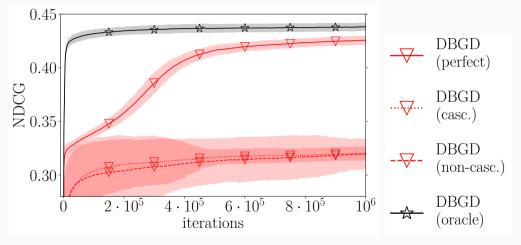
• We prove that its assumptions cannot be true for standard ranking models.

Then we reproduce the comparison under different conditions using simulation:

- Both cascading and non-cascading click behaviour.
- Simulated conditions ranging from ideal to extremely difficult:
 - ideal: no noise, no position bias,
 - near-random: mostly noise, very high position bias.

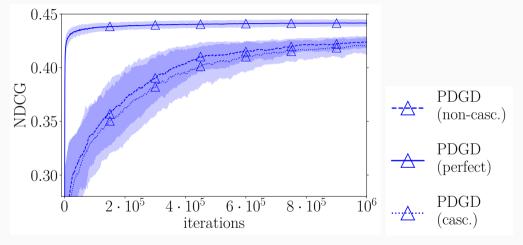
Experimental Results

Comparison: Dueling Bandit Gradient Descent



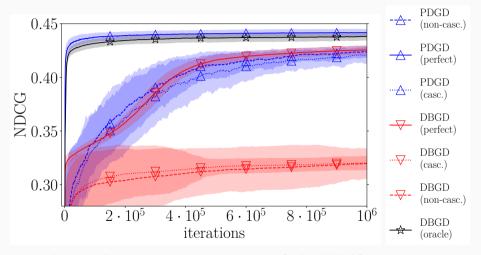
Results from simulations on the MSLR-WEB10k dataset.

Comparison: Pairwise Differentiable Gradient Descent



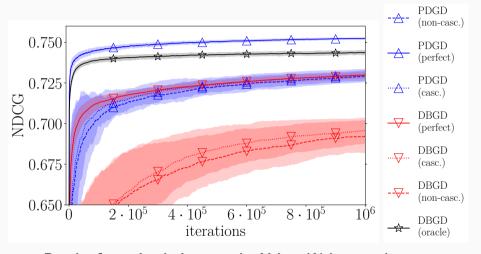
Results from simulations on the MSLR-WEB10k dataset.

Comparison: Complete



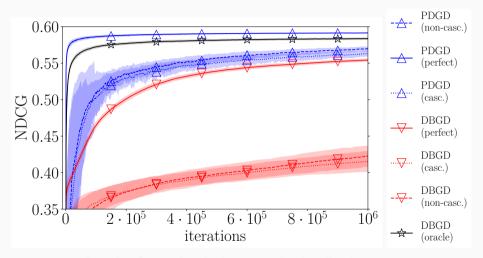
Results from simulations on the MSLR-WEB10k dataset.

Comparison: Complete



Results from simulations on the Yahoo Webscope dataset.

Comparison: Complete



Results from simulations on the Istella dataset.

Conclusion

Conclusion

In this reproducibility paper we have:

- shown that an existing proof for regret bounds is unsound.
- Reproduced a comparison between Pairwise Differentiable Gradient Descent and Dueling Bandit Gradient Descent, and generalized their conclusions from ideal circumstances to extremely difficult circumstances.
- Shown that under all experimental conditions we could simulate, Pairwise
 Differentiable Gradient Descent outperforms previous methods by large margins.

Please continue our work: https://github.com/HarrieO/OnlineLearningToRank

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Acknowledgments





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